



ABU DHABI UNIVERSITY

MICROPROCESSORS AND FIRMWARE PROGRAMMING

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# Lab Report 5

## Controlling 7 Segment Display

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**Section 1**

June 27, 2012

## Abstract

In this Lab we controlled a seven segment display using a micro-controller. The display counted up every 1 second.

## 1 Introduction

A seven Segment Display has 8 connection legs. To show each character we have to decide whether to turn ON a particular LED segment or no.

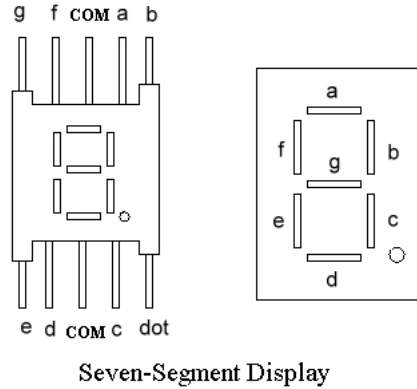


Figure 1: Pin configuration of 7 Segment Display

Not Connected	g	f	e	d	c	b	a	Numbers
1	1	0	0	0	0	0	0	0
1	1	1	1	1	0	0	1	1
1	0	1	0	0	1	0	0	2
1	0	1	1	0	0	0	0	3
1	0	0	1	1	0	0	1	4
1	0	0	1	0	0	1	0	5
1	0	0	0	0	0	1	0	6
1	1	1	1	1	0	0	0	7
1	0	0	0	0	0	0	0	8
1	0	0	1	0	0	0	0	9
A7	A6	A5	A4	A3	A2	A1	A0	PORTA PINS

Figure 2: Chart showing which Segments to turn On

## 2 Experiment Set-up

The ATmega16 chip was already mounted on a safety bracket. We had to place the bracket with the micro-controller on to the breadboard. Then we connected the micro-processor to each segment and also connected VCC to the common pin. *Figure 3*

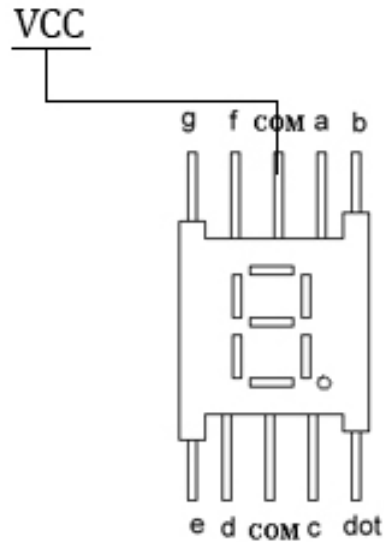


Figure 3: This is how we connect LEDs and the push buttons to the ATmega16

## 3 List of Equipment used

- ATmega16 micro-controller chip.
- JTAG MKII programmer.
- Wires.
- Breadboard.
- Mounting bracket for micro-controller.
- 7 Segment Display.
- 5V power supply.
- AVR Studio IDE.

## 4 Procedure

### 4.1 Describing the Inputs and Outputs

Table 1: Inputs, Outputs, and States

States	Inputs	Outputs
Show 0	Timer 0	Segment A
Show 1		Segment B
Show 2		Segment C
Show 3		Segment D
Show 4		Segment E
Show 5		Segment F
Show 6		Segment G
Show 7		Timer 0
Show 8		
Show 9		

### 4.2 Writing Code.

- Start AVR Studio and click on File/New/New Project.
- Write the following code into the AVR .c file.

```
#include <avr/io.h>
#include <avr/interrupt.h>
int count;
count = 0;
int current;
int numbers[] =
{
0b11000000,    \\0
0b11111001,    \\1
0b10100100,    \\2
0b10110000,    \\3
0b10011001,    \\4
0b10010010,    \\5
0b10000010,    \\6
0b11111000,    \\7
0b10000000,    \\8
0b10010000,    \\9

}

ISR (TIMER0_OVF_VECT)
{
    TCNT0 = 155;
```

```

        count++;
        if (count == 10000)
        {
            if (current == 9)
            {
                current = 0;
            }
            else
            {
                current++;
            }
            count = 0;
        }
    }

}

int main()
{
    TCNT0 = 155;
    TIMSK = 0b00000001;
    OCRO = 0x00;
    DDRB = 0xFF;
    GICR = 0b01000000;
    MCUCR = 0b00000011;

    current = 0;
    switch (current)
    {
        case 0: PORTB = numbers[0]; break;
        case 1: PORTB = numbers[1]; break;
        case 2: PORTB = numbers[2]; break;
        case 3:     PORTB = numbers[3]; break;
        case 4:     PORTB = numbers[4]; break;
        case 5:     PORTB = numbers[5]; break;
        case 6:     PORTB = numbers[6]; break;
        case 7:     PORTB = numbers[7]; break;
        case 8:     PORTB = numbers[8]; break;
        case 9:     PORTB = numbers[9]; break;
    }
}

```

### 4.3 Uploading the code to ATmega16.

- Connect JTAG to the computer through a USB cable and connect the JTAG Pins to the micro-controller.
- connect the Seven segment to the Atmega port B.

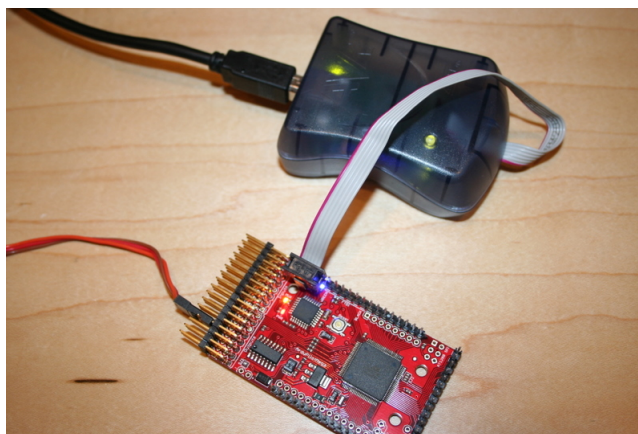


Figure 4: Connecting JTAG MKII to the ATmega 16

- Click build and compile in AVR Studio.
- Run the code.

## 5 Results and Discussions

At the end of these exercises we got the following results:-

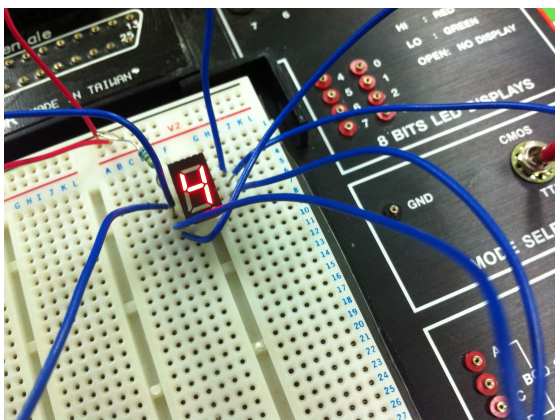


Figure 5: Seven Segment display is showing 4.

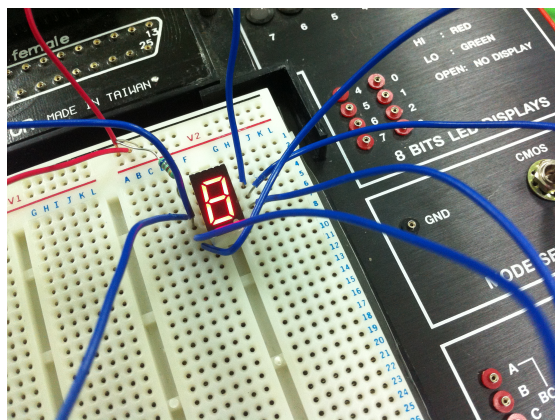


Figure 6: Seven Segment display is showing 8.

- Successful operation of seven segment display.
- If we use timer0, which is a hardware clock, it keeps the micro-controller less busy and allows it to perform other functions.
- For enabling interrupts we have to call a function sei()
- For using interrupts we have to include a header file “avr/interrupt.h”.
- TCCR0 stands for Timer Counter Control Register, which controls the timer clock and also enables it.
- Every digit incremented after 1 second.

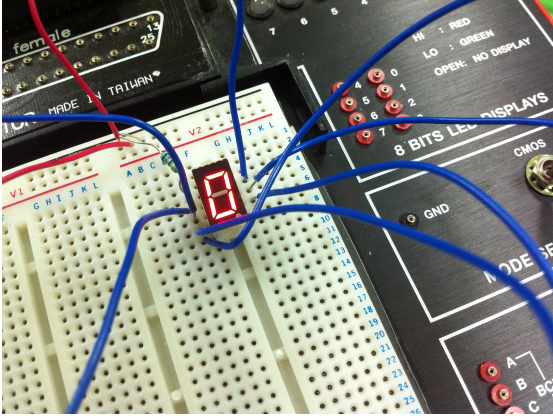


Figure 7: Seven Segment display is showing 0.

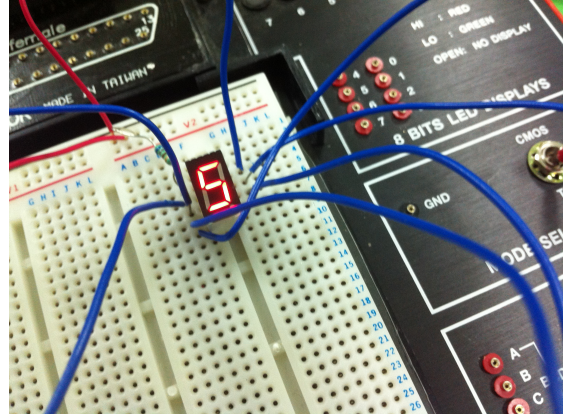


Figure 8: Seven Segment display is showing 5.

## 6 Conclusion

- All the segments have to be connected to the Port B because, we have set the Port B as output and not the other ports.
- If a pin is low, ie. grounded, it would light up.
- The ATMEGA16 has 3 hardware timers for performing several operations.

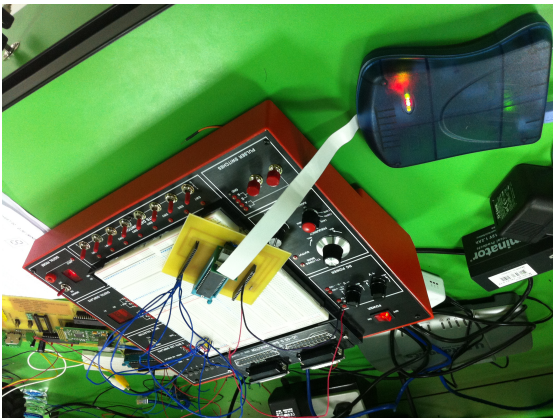


Figure 9: East-West is green while North-South is Red.

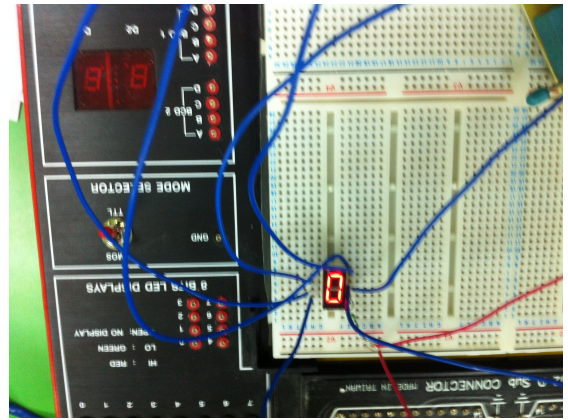


Figure 10: East-West is in warning state after being Green for 30 seconds